

# **P A N E L**

## **Trends in Networking and Services**

**ICNS 2009**

**Cancun**

**March 7-12, 2010**

# Guests

## **Moderator:**

**Petre Dini, IARIA, USA // Concordia University, Canada**

## **Guest Panelists:**

**Miklós Molnár, IRISA, INSA Rennes, France**

**Juan Flores, Universidad Michoacana, Mexico**

**Jaime Lloret, Polytechnic University of Valencia, Spain**

**Srikant Akella Vardhana, Infosys Technologies Ltd., India**

# Facts and Questions

## Facts

- there are adaptive components and adaptive systems
- some of them might have 'brain', some not, yet still adaptive
- there are agent-based mechanisms, self-learning mechanisms, leading to certain autonomy

## Questions:

- ? what is the core feature set towards evolving systems?
- ? what is the distance between utopia and realism, in dreaming/designing self-evolving systems?
- ? are there any methodology/guidelines for building such systems?

?

Panel: Robustness and Trust in Autonomic System

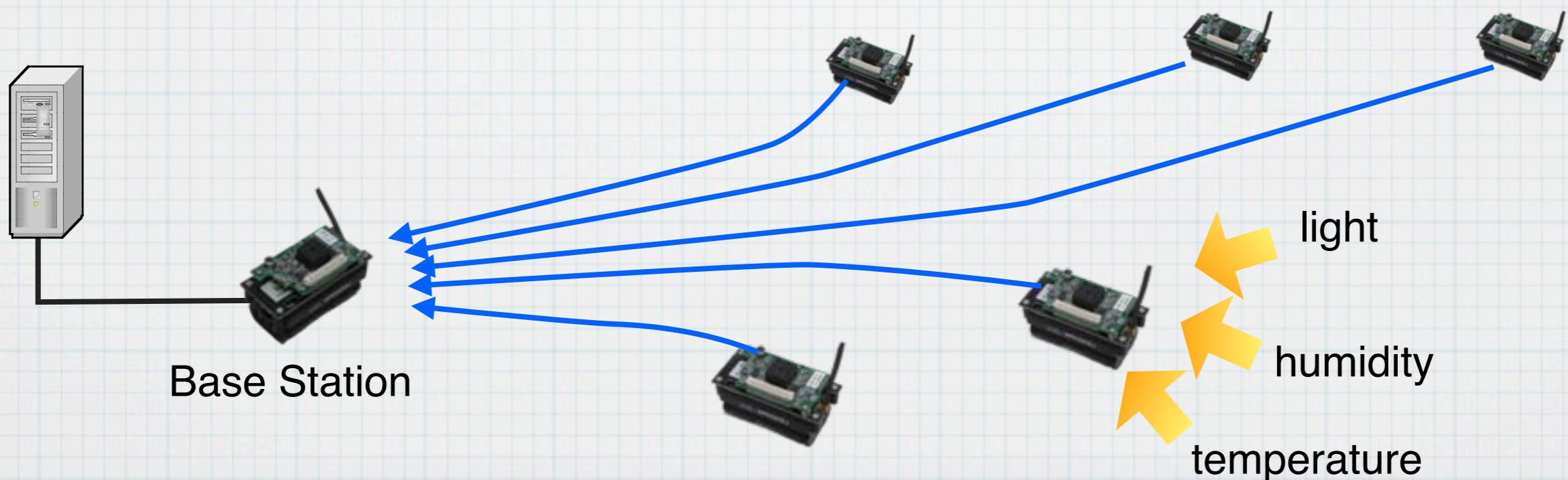
# Robustness and Trust in Autonomous Power Saving on the Sensor Networks

Toshio Hirotsu (Hosei Univ., Japan)

Mar. 9<sup>th</sup>, 2010

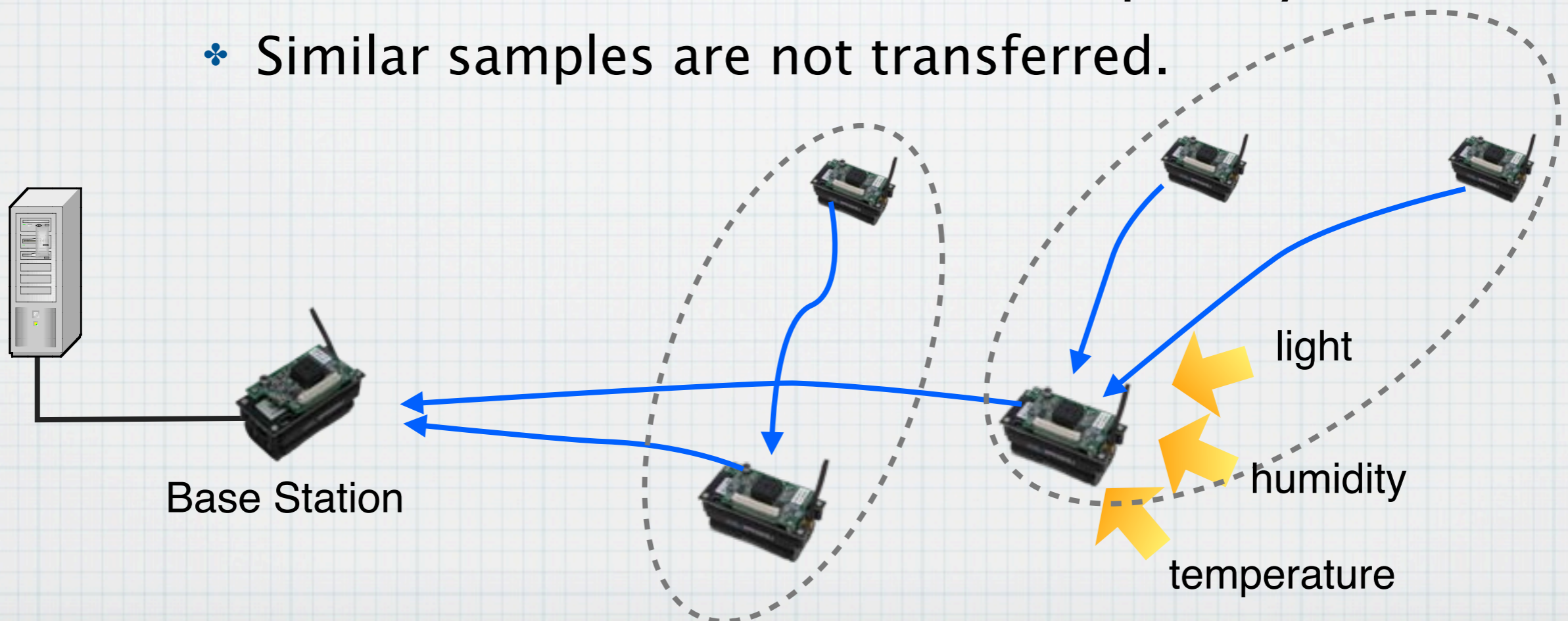
# Wireless Sensor Networks (WSN)

- ❖ Gathering the sensed environmental information
  - ❖ temperature, humidity, light, acoustic, ....
- ❖ Wireless communication to the base station
  - ❖ Nodes can be located arbitrary position.
- ❖ Battery powered
  - ❖ Control of the power consumption is important.



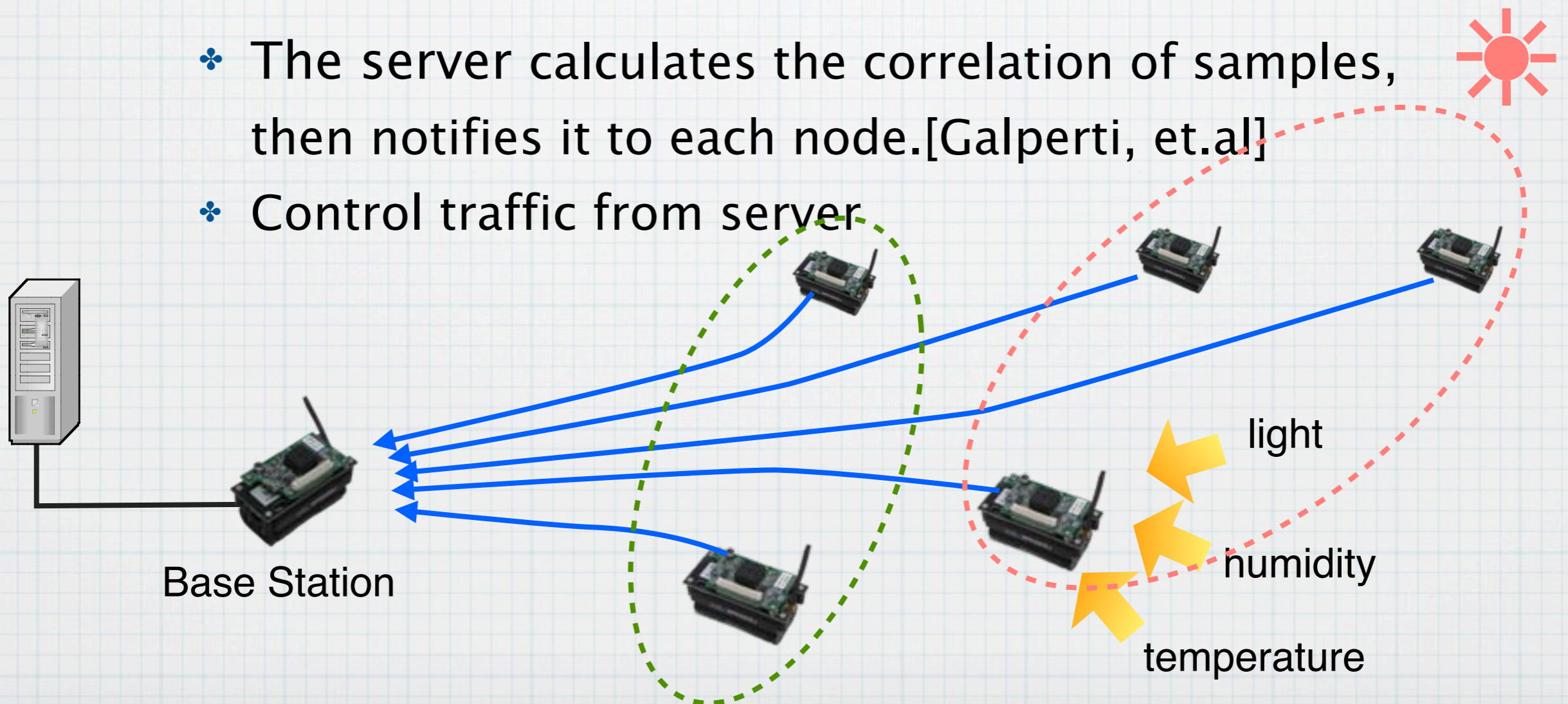
# Power Saving on WSN

- ❖ Controlling power on the radio communication
  - ❖ Reduction of the total distance ... clustering
  - ❖ Reduction of data size
    - ❖ Nodes sensing similar results construct a cluster.
  - ❖ Reduction of communication frequency
    - ❖ Similar samples are not transferred.



# Power Saving on WSN

- ❖ Controlling power on sensing (sampling)
  - ❖ Reduction of sampling frequency
    - ❖ This may suffer the quality of the sampled data.
  - ❖ Centralized control
    - ❖ The server calculates the correlation of samples, then notifies it to each node. [Galperti, et.al]
    - ❖ Control traffic from server



# Autonomous Power Saving Control

- ❖ To keep the battery lifetime longer...
  - ❖ Power on communication module
    - ❖ Reduction of the distance between node
    - ❖ Reduction of the volume of data
    - ❖ Reduction of the frequency of data transfer
  - ❖ Power on sensing device
    - ❖ Reduction of the frequency of sampling
- ❖ Large number of nodes work together.
  - ❖ It is hard to manage/calibrate per-node basis.

**Autonomous and self-optimized control is desirable.**



# Robustness in Autonomous Power Saving

## ❖ Centralized Control

- ❖ Efficient and precise control can be achieved with enough computation power and data.
- ❖ Lack of some special nodes may degrade the control.

## ❖ Decentralized Control

- ❖ Good control scheme is required.
  - ❖ It need to work under low computation power with small amount of data.
- ❖ Lack of any nodes suffer the control of the power consumption of the whole network.

# Trust in Autonomous Power Saving

- ❖ Quality of gathered data
  - ❖ Schemes related to the radio communication
    - ❖ Fixed interval (in usual)
    - ❖ The interval is decided by each application's request.
  - ❖ Schemes changing the sampling rate
    - ❖ Variable interval: it depends on the fluctuation of sampled results.
    - ❖ This scheme may drop the data when the interval becomes large.

---

# ROBUSTNESS AND TRUST IN AUTONOMIC SYSTEMS

Panel @ ICAS 2010

Marc Zeller, Fraunhofer Institute for Communication Systems ESK

---

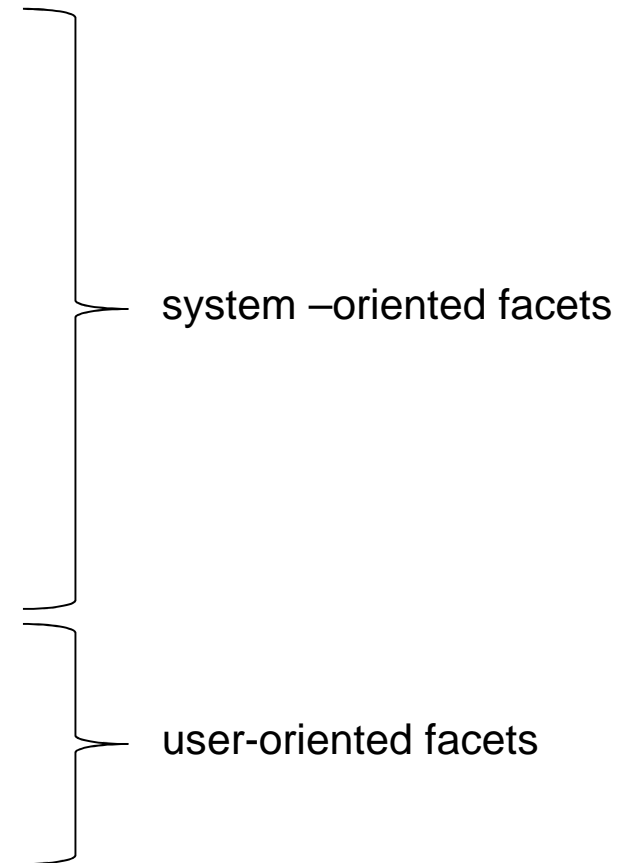
# Robustness and Trust in Autonomic Systems

- "Robustness is the invariance of [a property] of [a system] to [a set of perturbations]" (Alderson et al. 2007)
  
- Self-managing / autonomic artificial (engineered) systems provide a "natural" robustness to changes and failures
  - Systems with self-healing properties contain intrinsic recovery capabilities
  - Robustness also realized in many "traditional" systems
  
- Important is the **degree of robustness** the autonomic system exposes
  - Which failures can be "repaired" by the system itself?
  - The degree of robustness is an essential part of **Trust**

# Robustness and Trust in Autonomic Systems

Trust in autonomic systems is an umbrella term for:

- Functional Correctness
  - Does the system actually do what it should do?
- Safety
  - Will there be any undesired effects?
- Security
  - Does the system prevent any unauthorized access?
- Robustness / Reliability
  - What is the probability that a service is available when it is needed?
- Credibility
  - Does the system fulfill legal requirements? (e.g. in the automotive or aviation domain)
- Usability



# Robustness and Trust in Autonomic Systems

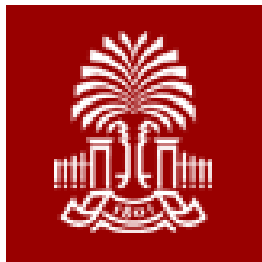
- Autonomic systems are highly dynamic, composed of a vast number of changeable components and are located in an ever changing environment
  - Important: Users must learn to trust such systems
  
- Main focus must be to develop **trustworthy** autonomic / self-managing systems
  - Systems which exhibit the desired behavior and prevent unwanted behavior (“Controlled Self-Organization”)
  - Systems which are trusted by the end-user
  - Systems which can be certified (e.g. fulfill certain regulations)
  - Systems which provide their services even under various disturbances (e.g. failures)

# Robustness and Trust in Autonomic Systems – Future Research Directions

---

**Yiming Ji and Lei Chen**

**Emails:** [yimingji@uscb.edu](mailto:yimingji@uscb.edu) and [chen@shsu.edu](mailto:chen@shsu.edu)



University of South Carolina Beaufort

**Sam Houston State University**



# Future Research Directions (I)

---



- More effective radio propagation models
  - Provides dynamic radio estimation for 3-D environments
  - Consider representative indoor objects (desks, chairs, doors, windows, different partitions,....)
  - Consider impacts from weather / temperature / pressure or others



# Future Research Directions (II)

---



- Impact of Radio Dynamics or Perturbations on the performance of indoor systems
  - Radio attacks, or non-cryptographic attacks that modify radio signals at reference landmarks
  - Impacts and solutions
  - This affects not only indoor location determination systems, but it is also an interesting direction for general sensor networks



## Future Research Directions (III)

---

- Mobility modeling – these are the common factors considered
  - velocity
  - direction
  - Vehicles, pedestrians, others
- Security in mobile networks
  - Lightweight
  - Limited power
  - Range
  - etc.