HD VS. 4K DRIVEN REMOTE TOWER OPTICAL SYSTEMS WHAT IS THE BETTER OPTICAL SENSOR?

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TART





Conventional Remote Tower





Remote Tower Controller Working Position at RTC Leipzig Source: DFS GmbH





Characteristics of Full HD and 4K Cameras



- Senzor Size and Light Sensitivity
- Bandwidth and Processing Resources
- High Dynamic Range





Camera Specs

	HD	4K-1	4K-2	
Lens	F1.4	F1.7	F1.4	
HDR	yes	yes	yes	
Image sensor size	1/2 inch (12,7 mm)	4/3 inches (33,9 mm)	$1^{3}/_{8}$ inches (35 mm full frame)	
FoV [p]	1920 x 1080	3840 x 2160	3840 x 2160	
rov [þ]	Full HD	UHD	UHD	
FoV [°]	43° x 24°	60° x 33°	54° x 32°	
Resolution in pixel per degree [ppdeg]	45	65	68	
Total number of pixels	2,073,600	8,294,400	8,294,401	
Target frame rate (fps)	30	30	30	
Total number of pixels per second (pps)	62,208,000	248,832,000	248,832,001	
Vide o compression	H.264 High	H.264 High	H.264 High	
Max bitrate [Mbit/s]	50	50	32	
Average max bit per 1000 pix per camera	804	201	129	





EDVE Airport Map





Hypotheses

- H_{0,1}: There are no differences between HD and 4K cameras in terms of their detection range performance.
- H_{0,2}: There are no differences between HD and 4K cameras in terms of their recognition range performance.
- H_{0,3}: There are no differences between HD and 4K cameras in terms of their perceived video quality



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7 different weather/visibility with ILS RWY26 approaches

III III III III

Detection

Gesichtet

- CAVOK with Clouds*
- Blue Sky
- Opposite-Sun
- Rain
- Dusk

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- Significant Clouds**
- Low Visibility



*



3 different weather/visibility conditions with VFR approaches via November 1 & 2



- CAVOK Sun-yes Clouds-No
- CAVOK Sun-yes Clouds-Yes
- CAVOK Sun-No Clouds-Yes





Experimental Set Up





 Detection & Recognition
 Range
 performance

Experimental Set Up (Video Quality)





- Motion: Movements smooth vs. flickering
- Noise: noise vs. noise-free
- Color: colors bleeding vs. natural
- Edges: blurring vs. sharp
- Textures: blurring vs. sharp

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Results

- RWY26 <u>Detection</u> Range Performance [nmi]
- via "Cam" and "Weather" condition

distance from camera (nmi)											cam	1 4К-1 4К-2 HD
0 -	blue	sky	CAVOK	cloud	ds	dusk veathe	low_vi:	s ra	in	sun		

	df n	df d	F	р		η^2_G
Cam	2.00	14.00	2.017	0.170		0.027
Weather	1.57	10.97	489.115	0.000	***	0.965
Cam*Weather	12.00	84.00	6.434	0.000	***	0.208

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Results

- November 1&2
 <u>Detection</u> Range
 Performance [nmi]
- via "Cam" and "Weather" condition

Weather	Cam	nmi
CAVOK Sun-yes_clouds-no	4K-1	2,74
	4K-2	2,18
	HD	1,97
CAVOK Sun-yes_clouds-yes	4K-1	3,33
	4K-2	3,18
	HD	3,66
CAVOK Sun-no_clouds-yes	4K-1	3,37
	4K-2	3,46
	HD	3,39

		Cameras								
		4K-1	4K-2	HD						
V	CAVOK									
i	Sun-yes									
s ;	Clouds-no									
ı h	CAVOK									
i	Sun-yes									
l	Clouds-yes									
i	CAVOK									
t	Sun-no									
У	Clouds-yes									

Pie Chart Matrix for Detection Performance for Small Aircraft (grey = "detected", white = "not detected")



Results

- RWY26 <u>Recognition</u> Range Performance [nmi]
- via "Cam" and "Weather" condition



	df_n	df_d	F	р		η^2_G
Cam	2	10	12.720	0.002	**	0.136
Weather	6	30	29.801	0.000	***	0.644
Cam*Weather	12	60	5.286	0.000	***	0.224

Results Perceived Video Quality (general)





pairwise t-tests

							p-			
Group 1	Group 2	nl	n2	t	df	р	adjusted		D	95% CI
4K-2	HD	126	126	3.33	125	0.001	0.003	**	0.294	[0.119, 0.468]
4K-2	4K-1	126	126	-2.15	125	0.033	0.100		-0.206	[-0.017, -0.396]
HD	4K-1	126	126	-5.10	125	0.000	0.000	***	-0.500	[-0.306, -0.694]



cam Boxplot diagrams with median and IQRs showing the ratings for three different cameras via all 10 weather/visibility conditions and all video quality categories

Results Readability of the Lettering sign





pairwise t-tests

							p-			
Group 1	Group 2	nl	n2	t	df	р	adjusted		D	95% CI
4K-2	HD	126	126	18.6	125	0.000	0.000	***	1.440	[1.290, 1.600]
4K-2	4K-1	126	126	-0.36	125	0.723	1.000		-0.040	[0.182, -0.261]
HD	4K-1	126	126	-12.0	125	0.000	0.000	***	-1.480	[-1.240, -1.730]

Boxplot diagrams with median and IQRs via three different cameras for over all seven RWY26 weather/visibility conditions

Conclusions & Outlook



- no 100% clear answer
- Detection & Recognition differences in this setting were rather marginal
- slight advantages for the 4K camera
- 4K cameras in this setting deliver a better perceived video quality
- In a 360° composition of several individual cameras it is to be expected that the slight advantages of 4K technology would become even more apparent
- Codec H.264/H.265 or AVI) and bitrate needs to be investigated in a separate study



THE END

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