

DigitalWorld 2024 May 26th-30th, 2024 Barcelona, Spain



Playing with the ThinkMind Corpus

Lasse Berntzen

University of South-Eastern Norway

Open data

Open source movement

• Software should be free

Open data

• Data should be free

History

- Before 2011 IARIA conferences were published by IEEE CPS
- In 2010 it was decided to move to Open Access
- From 2011 all contributions from all IARIA conferences are available from thinkmind.org
- The truth is: IARIA has been a pioneer in Open Access

The ThinkMind Corpus

25.76 GB or information

38.435 files including index pages

As of May 28th, 2024

Indexing and searching

- Indexing services are somewhat unpredictable
- Driven by money and politics
- It is the same with search engines
- Driven by money and politics
- Open access is now a battleground

Three student projects

Searching the ThinkMind corpus

Visualizing research collaboration

A ThinkMind ChatGPT

Searching the ThinkMind Corpus

Students: Rakhman Ruslanovich Alkhazurov, Mikael Fossli, Rinor Krasniqi, Tor Einar Horntvedt Molland

Supervisor: Lasse Berntzen

Aim

- To create a better user interface for the IARIA ThinkMind library
- Testing of existing web site to identify weaknesses
 - Incomplete search results
 - Outdated layout
 - Some accessibility issues (colors)
- Need for a better searching mechanism
- Creating a better user experience (UX)

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A ICDS 2024

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InfoSys 2025 Congress March 09, 2025 to March 13, 2025 -

- Lisbon, Portugal
 - ICNS 2025, The Twenty-Second International Conference on Networking and Services
 - ICAS 2025, The Twenty-Second International Conference on Autonomic and Autonomous Systems
 - ENERGY 2025, The Fifteenth International Conference on Smart Grids, Green Communications and IT Energyaware Technologies
 - WEB 2025, The Thirteenth International Conference on Building and Exploring Web Based Environments
 - DBKDA 2025, The Seventeenth International Conference on Advances in Databases, Knowledge, and Data Applications
 - <u>SIGNAL 2025</u>, The Tenth International Conference on Advances in Signal, Image and Video Processing
 - <u>BIOTECHNO 2025</u>, The Seventeenth International Conference on Bioinformatics, Biocomputational Systems and Biotechnologies
 - <u>AIHealth 2025</u>, The Second International Conference on AI-Health

InfoWare 2025 Congress

March 09, 2025 to March 13, 2025 -Lisbon, Portugal

> ICCGI 2025, The Twentieth International Multi-Conference on Computing in the Global Information Technology

Think Mind

Lasse Berntzen

IARIA Congress 2025

July 6 - 10, 2025 - Athens, Greece

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submission deadline: March 18, 2025

ThinkMind // ...

Journals

IntSys ::: International Journal On Advances in Intelligent Systems

IntTech ::: International Journal On Advances in Internet Technology

LifSci ::: International Journal On Advances in Life Sciences

NetSer ::: International Journal On Advances in Networks and Services

Sec ::: International Journal On Advances in Security

Soft ::: International Journal On Advances in Software

SysMea ::: International Journal On Advances in Systems and Measurements

Tele ::: International Journal On Advances in Telecommunications

Conferences

ACCESS ::: International Conference on Access Networks

ACCSE ::: International Conference on Advances in Computation, Communications and Services



Search result

About 1 results (0.29 seconds)

Citizens as Sensors - UPV

www.thinkmind.org > download



File Format: PDF/Adobe Acrobat Lasse Berntzen,. Marius Rohde Johannesen. School of Business. University of South-Eastern Norway. Horten, Norway e-mail: lasse.berntzen@usn.no marius ...

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Reduction of Dental Anxiety and Pain in Children using Robots

 $Robotics-dental\ treatment-WoZ\ experimentation-human\ robot\ interaction-multi-modal\ interaction-healthcare\ robotics$

 ${\tt Mine Yasemin - Yelda Kas \ddot{A}\pm mo\ddot{A}lu - Simin Kocaoglu - Emine Karsli - Elif Bahar Tuna Ince - Gokhan Ince - Simin Kocaoglu - Emine Karsli - Elif Bahar Tuna Ince - Sokhan Ince -$

In this study, we aim to use humanoid robots to implement a techno-psychological distraction technique for children between 4-10 years of age in order to reduce their anxiety and stress-related pain during their dental treatment. A multi-modal system supporting audio-based dialogues, videos, gestures and expressions based on face, head, arm, body movements have been developed for a robot. We have employed the Wizard-of-Oz technique, a popular approach in human robot interaction research. The effectiveness of the system is shown by carrying out experiments on two groups of children, one group whose treatment is conducted by the dentistâs own skills alone, the other whose treatment is conducted by a dentist with the assistance of the robot. In order to evaluate the robota's effect on the anxiety and fear of children during these experiments, procedures with no anesthesia (not requiring the use of needles) have been carried out. The system has been evaluated subjectively by applying a variety of questionnaires to patients, and dentists as well as objectively by measuring patient's heart rates.

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Reduction of Dental Anxiety and Pain in Children using Robots Robotics — dental treatment — WoZ experimentation — human robot interaction — multi-modal interaction — robotics Mine Yasemin — Yelda KasımoÄlu — Simin Kocaoglu — Emine Karsli — Elif Bahar Tuna Ince — Gokha In this study, we aim to use humanoid robots to implement a techno-psychological distraction technique for ch 410 years of age in order to reduce their anxiety and stress-related pain during their dental treatment. A multi supporting audio-based dialogues, videos, gestures and expressions based on face, head, arm, body movement developed for a robot. We have employed the Wizard-of-Oz technique, a popular approach in human robot int The effectiveness of the system is shown by carrying out experiments on two groups of children, one group wi conducted by the dentistas own skills alone, the other whose treatment is conducted by a dentist with the assis In order to evaluate the robotas effect on the anxiety and fear of children during these experiments, procedures anesthesia (not requiring the use of needles) have been carried out. The system has been evaluated subjectively variety of questionnaires to patients, and dentists as well as objectively by measuring patient's heart rates.	- healthcare in Ince ildren between modal system s have been eraction research. nose treatment is ance of the robot. with no y by applying a	< <p>Reduct ACHI+201 April 24 A Robu ICAS+2015 June 2, 2 Smart J INTELLI+2 May 22, Face D SIGNAL+2</p>	ion of Dental 2016 1st Polyuretha 2019 Factory Autor 2022 2022 etection on In	Anxiety and 2308-4138 ane Depositin 2308-3913 mation for Ro 2308-4065 and Thern	Showing 1 to Analysis and Des SERVICE+COMPUTATIO July 22, 2012 Mobile Robots P ICAS+2011 May 22, 2011 Digital Badges in ICTW+2013 June 23, 2013 Movel Nanopartic	a 12 of 1256 sign in Providing 2308-3549 2308-3549 2308-3913 3 1 Informal Learn 2308-3972 2308-3972 2308-3972	Bookmarked Articles ACCESS+2012 Optical Access Network Migration from GPON to XG-PON ACCESS+2011 Digital Complexity in DSL: An Extrapolated Historical Overview ACCESS+2012 A Novel MIMO-OFDM Scheme Based of Modulation Diversity for IEEE 802.11a Standard ACCESS+2012 Extending Neutrality to Experimental Facilities ACCESS+2011 Adaptive Resource Allocation Scheme for TETRA Networks with Multi-operators	★ 1 ★ onc ★ ★ or
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Searching



Data collection

- Two Python scripts:
 - Downloading, parsing, and data insertion of .htm files
 - Downloading, and data insertion of .pdf files

Architecture

Uses Fuse for fuzzy search, nodemon for automatic restart after changes

Visualizing Research Collaboration

Students: Martin Havsgård, Simen Sørlie Helgeby, Arman Asadi Laleh Christoffer André Oseberg, Herman Aleksander Solberg Supervisor: Marius Rohde Johannessen

Research collaboration

- Based on the following paper: Marius Rohde Johannessen, Lasse Berntzen. A Decade of eParticipation Research. 11th International Conference on Electronic Participation (ePart), Sep 2019, San Benedetto Del Tronto, Italy. pp.3-14 (Springer)
- Checked for collaboration among researchers.
- Found several clusters
- Made manual visualizations

Aim

- Use the ThinkMind Corpus as a data source
- Automate visualizations

Co-Authorship Network Analysis

Co-Authorship Network Analysis

Nagel	*
Search	
	Nagel

Co-Authorship Network for Wolfgang E. Nagel

Author: Lasse Berntzen

Articles: 314, 385

Collaborators per article:

- Article 314 (Event: IntSys, Edition: IntSys+v9+n34+2016): Marius Rhode-Johannessen, Adrian Florea
- <u>Article 385</u> (Event: IntSys, Edition: IntSys+v12+n12+2019): Marius Rohde Johannessen, Rania El-Gazzar

Keywords:

smart cities (2) sensors (2) smart buildings sustainability research design smart decision-making big data analytics autonomous systems

PDF URLs:

- _/articles/intsys_v9_n34_2016_30.pdf
- _/articles/intsys_v12_n12_2019_3.pdf

Co-Authorship Network Analysis

Depth must be zero or a positive number

Move

focus

Co-Authorship Network Analysis

Libraries used

- Programmed in Python
 - Beautiful Soap (web scraping)
 - Pandas (handling data)
 - Fitz (handling .pdf)
 - Dash (for web application)
 - NetworkX (graphs)
 - Re (regular expressions)
 - Plotly (graphics)

A ThinkMind ChatGPT

Students: Aldar Ali, Mia Bergseter Jonsrud, Lars Wear Nilsen, Ema Sedyte Supervisors: Marius Rohde Johannessen and Lasse Berntzen

Aim

- By combining AI techniques with natural language processing and machine learning, the goal of the project was to develop a chatbot that could assist in finding the right documents from ThinkMind in an efficient and intuitive way.
- The chatbot answers questions about IARIA's published articles and their conferences.
 - For example, you can ask for information about a topic, an author, or a conference.
 - You can also link to the article(s) that the chatbot uses to answer the question.

Software and libraries

- BeautifulSoup4 og PDFMiner
- LangChain (framework for chatbot development)
- PineCon (vector database)
- OpenAIs Embedding and Large Language Model (LLM)
- NLTK (Natural Language Toolkit)
- Streamlit Frontend application development

https://youtu.be/KzHmMSz_ptk

Indexing

- First, the documents were loaded using DocumentLoaders
- The text was split into smaller pieces for indexing, and for the text to fit in the model's context window.
- The last step in the indexing was to embed these splits and store them in the vector database.

Vector database

Embedding

Retrieval and generation

- When a user asks a question to the chatbot, the retrieve function will find the best ranked bits from the vector database.
- The language model then produces an answer by building a new "prompt" that takes into account the original question and the data from the retrieve function.

TalkMind flow diagram

Workflow

🞯 Can you tell me anything about Bastøy?

I don't have information on Bastøy in the context provided. If you have any other questions or need information on a different topic, feel free to ask!

Ask me anything about thinkmind!

what is intelligent system 0

An intelligent system is a complex system that incorporates the concept of intelligent collaboration and autonomous behavior. It allows the system to evolve and be managed more easily. Intelligent systems are equipped with cognitive capabilities enabled by flexible control loops and cognitive algorithms, enabling them to act autonomously in an increasingly intelligent human-like manner. These systems can maintain multiple goals, perform context-sensitive reasoning, and make appropriate decisions based on complex and uncertain information, making them more robust in adapting to dynamic environments.

Can you provide examples of intelligent systems?Some examples of intelligent systems include IBM Watson, Amazon's Alexa, and various cognitive products that operate with flexible control loops and cognitive algorithms. These systems can perform context-sensitive reasoning, make appropriate decisions based on complex information, and adapt to dynamic environments.

tell me more about ibm watson

Can you provide more information about IBM Watson?IBM Watson is a supercomputer developed by IBM that gained significant attention when it competed on the game show "Jeopardy" in 2011. Watson's architecture is based on question-answering technology. In March 2018, IBM launched the IBM Watson Assistant platform, which allows users to create chatbots within their domain of knowledge. The platform enables users to deploy chatbots on various platforms like Slack or Facebook. Watson's capabilities include accessing and processing vast amounts of data to generate responses based on the input it receives, but it does not possess true intelligence or understanding of the information it processes. Watson demonstrates the power of artificial intelligence and natural language processing in information retrieval and response generation.

Can you describe the process of making a pizza?I don't have information on making pizza in the provided context.

Scope and Use: ChatGPT has been trained on a large corpus of diverse text from the Internet so that it can understand and generate responses on a wide range of topics.

The TalkMind chatbot's knowledge base is more limited, focusing on the specific topics or data in the ThinkMind library.

Understanding and context: ChatGPT excels at understanding context and generating human-like responses, while TalkMind can have more structured and predefined responses based on ThinkMind.

Availability and scalability: ChatGPT is available internationally and can handle a virtually unlimited number of simultaneous users.

TalkMind's availability and scalability are dependent on the hosting infrastructure and design.

Development and maintenance: ChatGPT is a pre-trained model that does not require continuous development or maintenance on the part of the user.

TalkMind chatbot may require continuous updates and improvements to the database, algorithms and integrations.

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Future plans

- Integrate the three projects into one
- Move to a cloud-based service
- Examine additional functionality
 - E.g. keyword use over time

Thank you for listening!

If you want to contribute or stay in touch: lasse.berntzen@usn.no